
SI-traceable laboratory calibration of seismometers with or without a Laser

Thomas Bruns

Dr. rer.-nat., Head of Dept. 1.7 “Acoustics and Dynamics”
Physikalisch-Technische Bundesanstalt (PTB), Germany



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Calibration ...

Establish a relationship between a reference standard (Ref) representing **the quantity** and **the indication** of the instrument to be calibrated (DUT).

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Primary Calibration: Reference is of a different kind than the Instrument to be calibrated. Usually the Reference is close(r) to the unit's definition.

Secondary Calibration: Reference is of the same kind as the DUT.



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Velocity (Input) \leftrightarrow Voltage (Output)

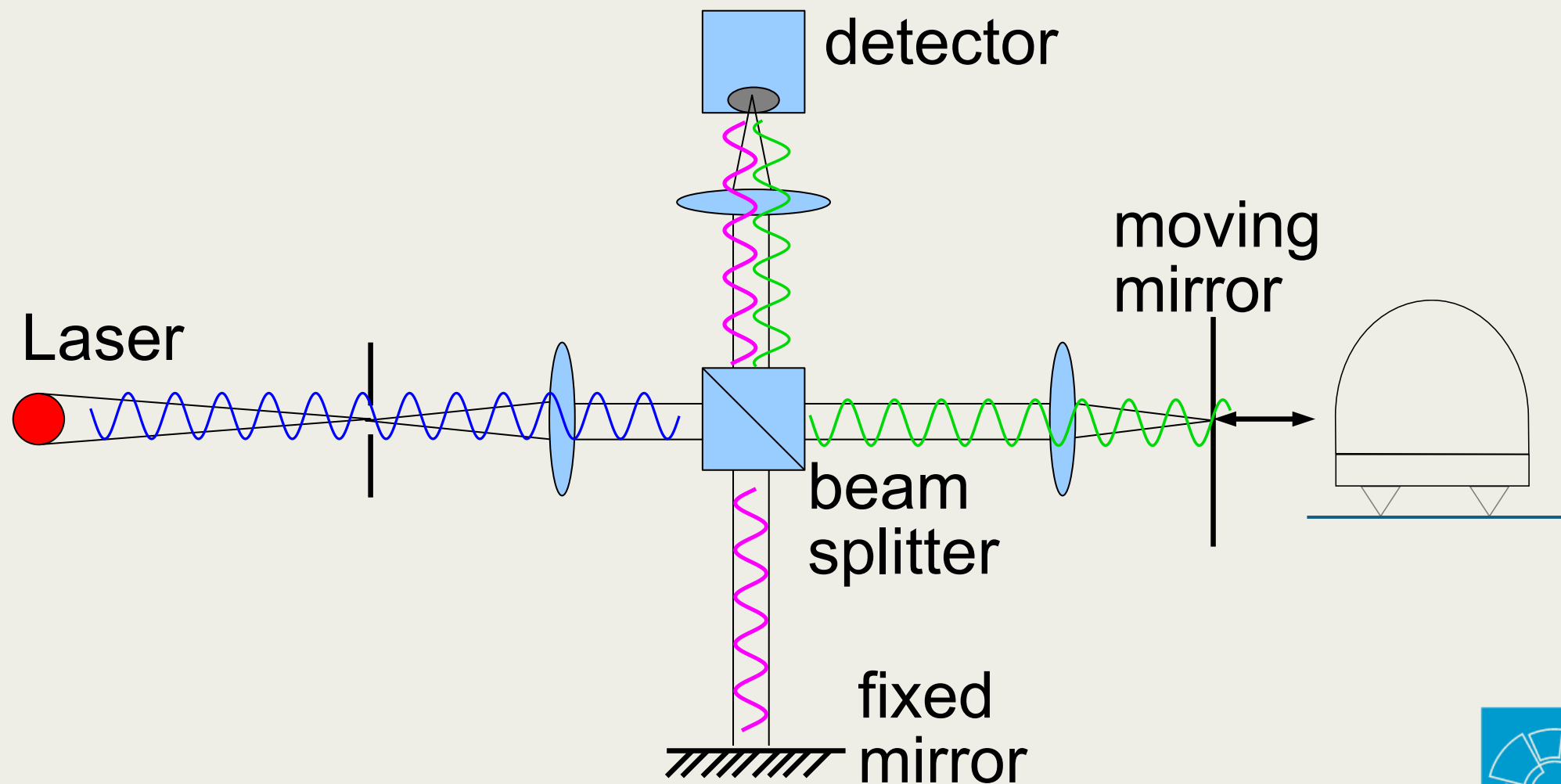
Primary Calibration: Reference is of a different kind than the Instrument to be calibrated. Usually the Reference is close(r) to the unit's definition.

Laser Interferometer \leftrightarrow Seismometer

Secondary Calibration: Reference is of the same kind as the DUT.

Seismometer \leftrightarrow Seismometer

Primary Calibration according to ISO 16063-11



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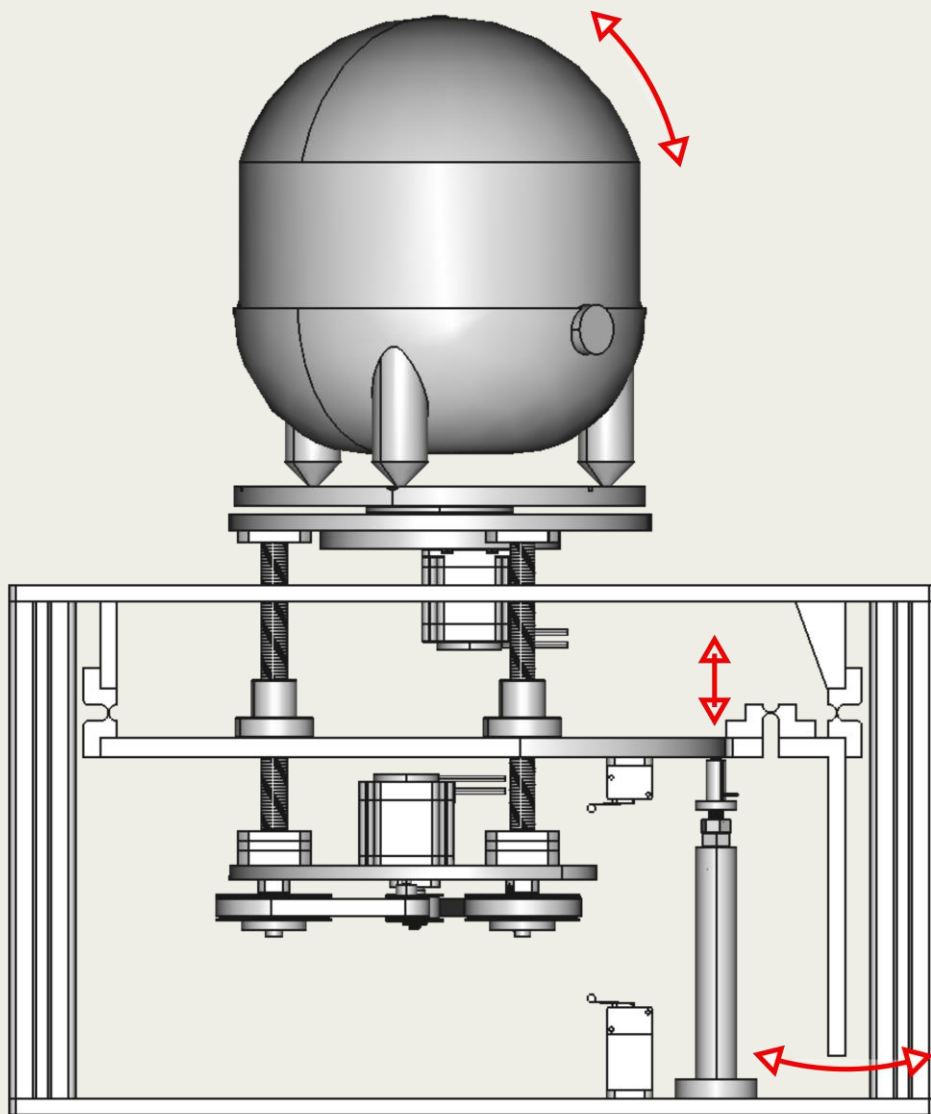




Primary Calibration according to ISO 16063-11

- Direct SI-traceable via Laser-wave length, time (sample rate) and Voltage
- Very precise, stable, reproducible. ...
- Measures only exactly straight motion (along line of Laser beam)
 - No accounting for **gravity disturbances** at low frequency (due to travel curvature)
 - No accounting for **dynamic tilt** at high frequencies (due to finite bearing stiffness)
 - No accounting for the position of the internal sensor (sensitive center)

Primary Calibration “similar” to ISO 16063-42



- (horizontal) calibration by dynamic tilt in the gravitational field.
- Traceable via tilt amplitude, g_{local} , time (sample rate), voltage
- Works for very low frequencies below 2 Hz.

Bruns et al., Metrologia 61 (2024) 055012 (8pp)
<https://doi.org/10.1088/1681-7575/ad795a>

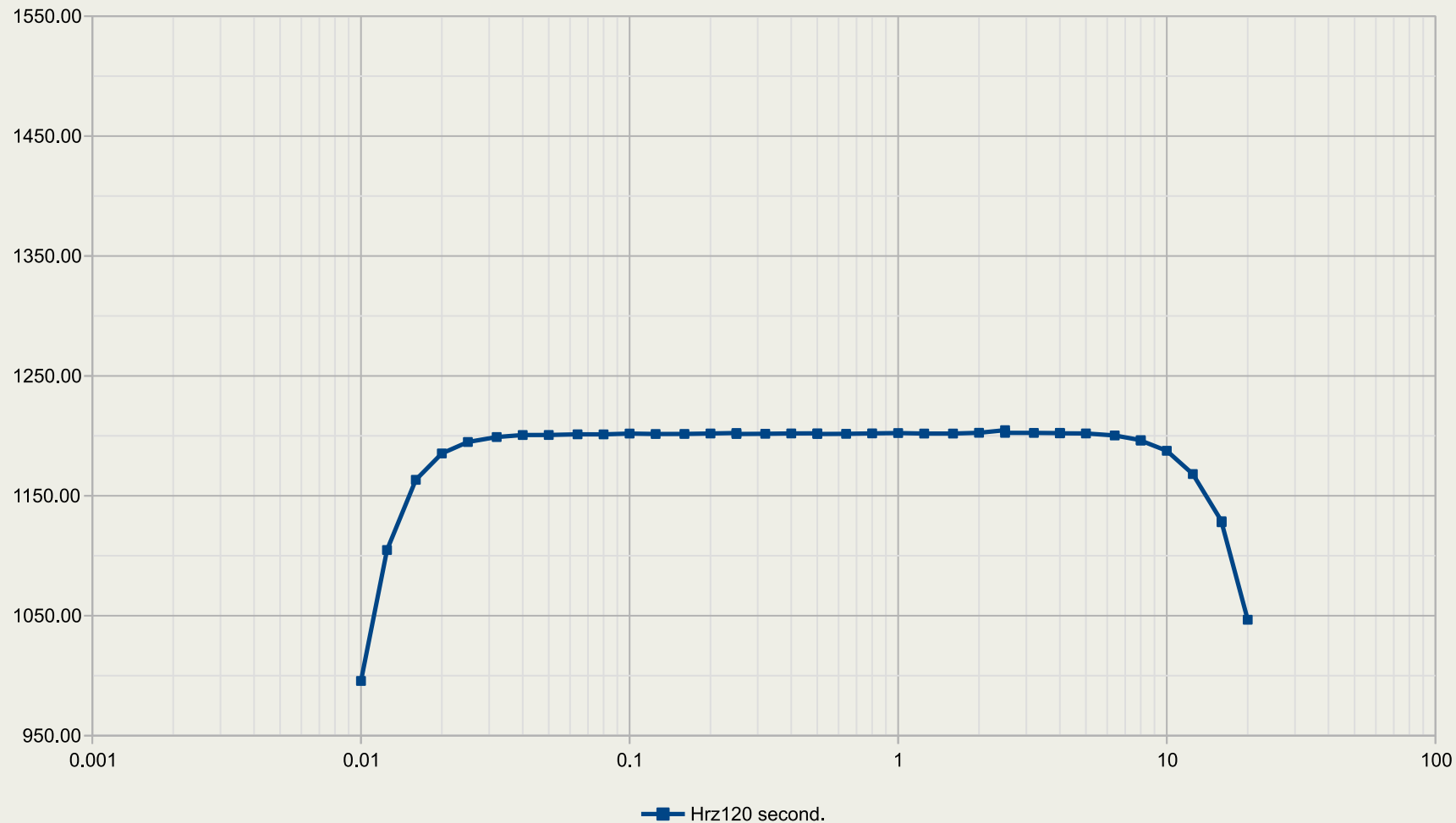
Comparison calibration according to ISO 16063-21





$$S_{\text{DUT}} = S_{\text{Ref}} \cdot \frac{\hat{U}_{\text{DUT}}}{\hat{U}_{\text{Ref}}}$$

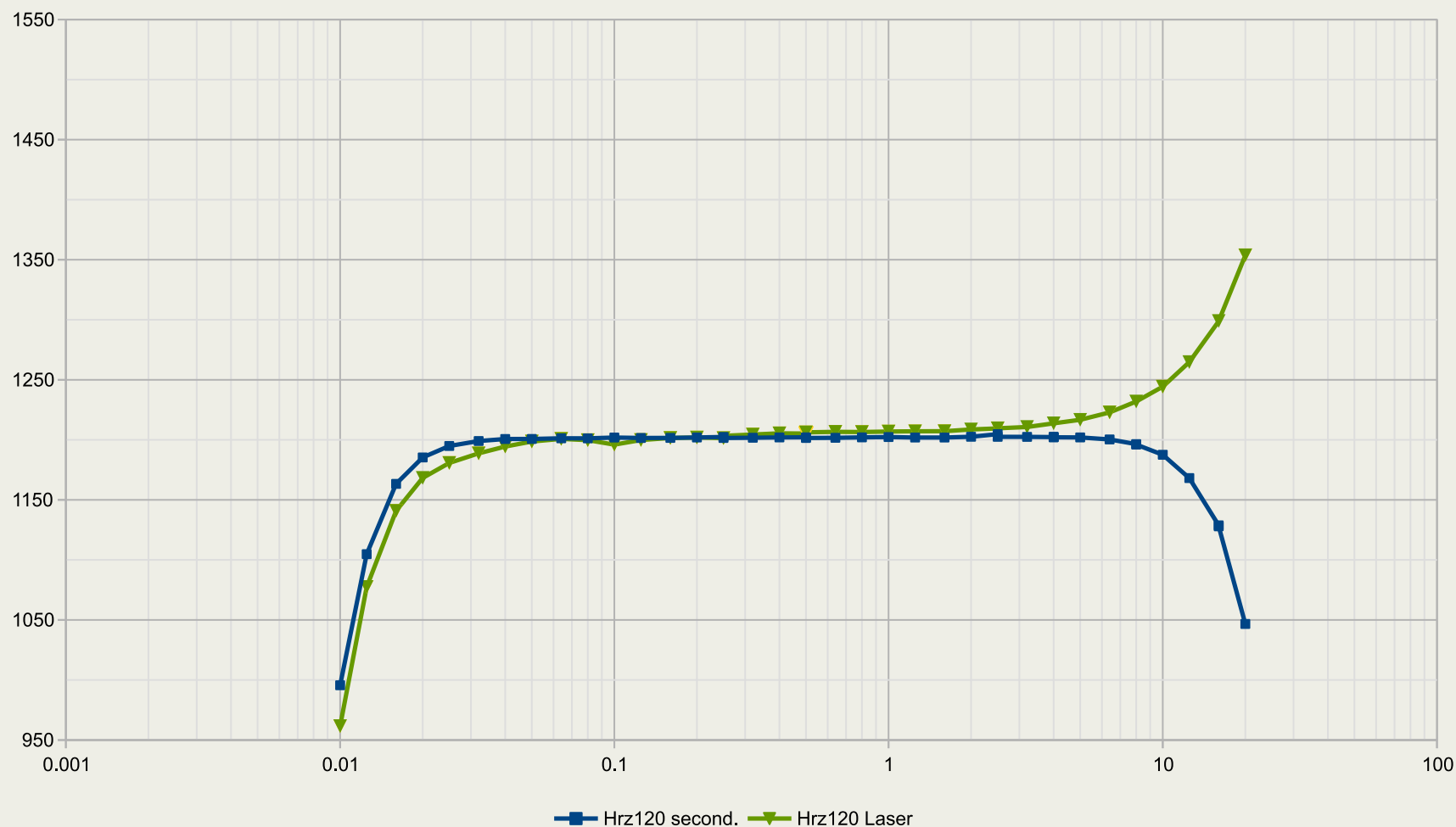
Comparison calibration **simple** approach





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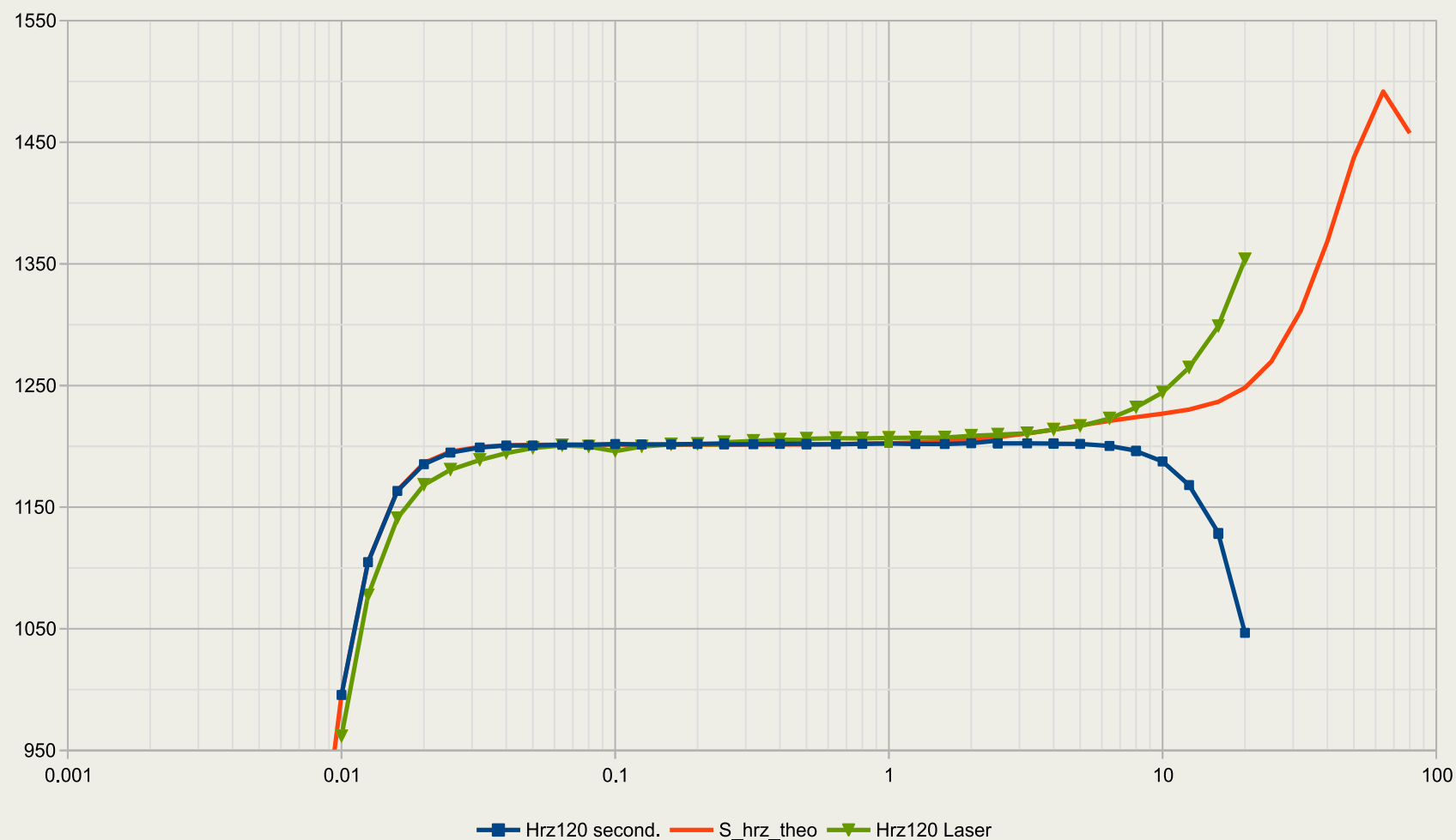
Comparison calibration **simple** approach



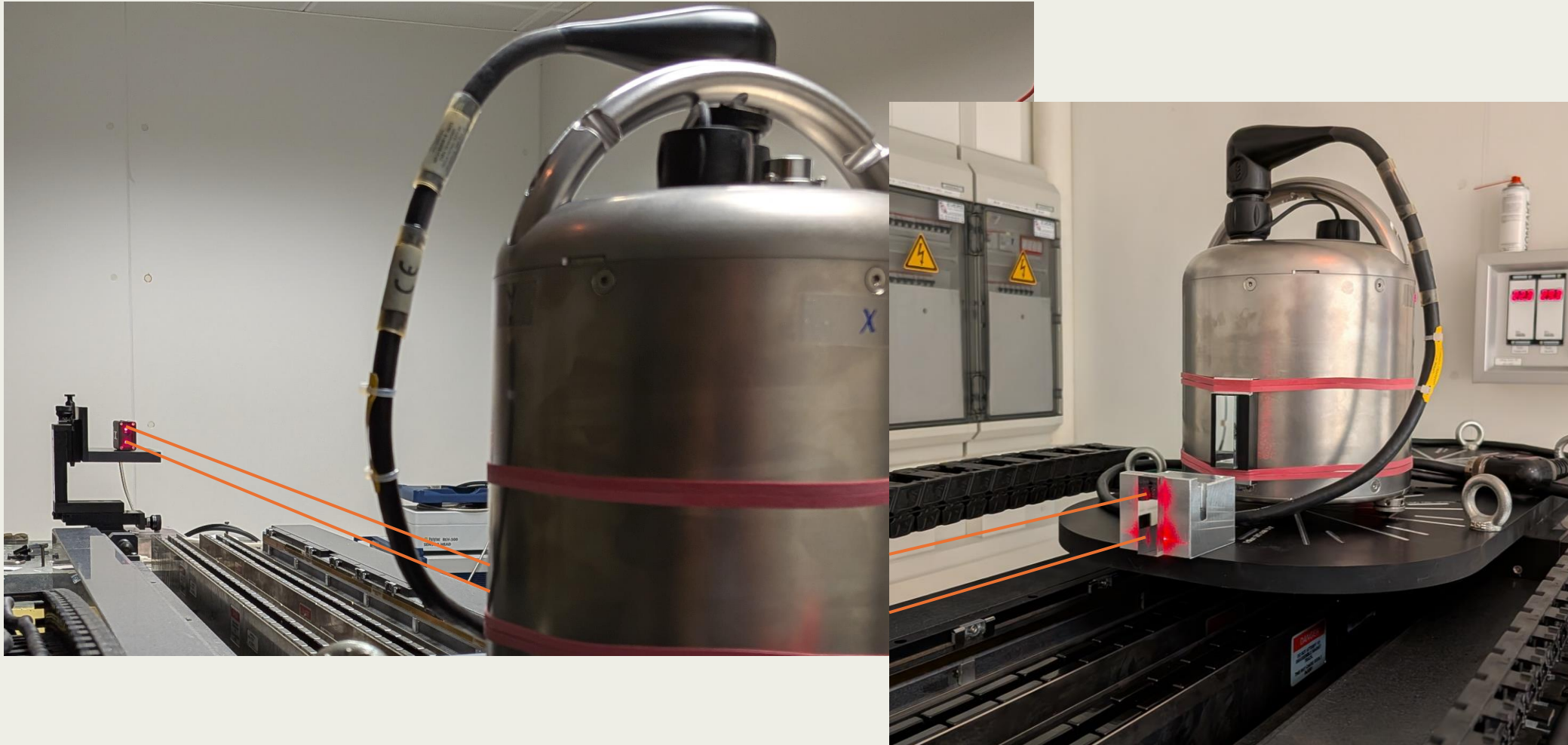


$$S_{\text{DUT}} = S_{\text{Ref}} \cdot \frac{\hat{U}_{\text{DUT}}}{\hat{U}_{\text{Ref}}} \quad ?$$

Comparison calibration **simple** approach



What happens here ?

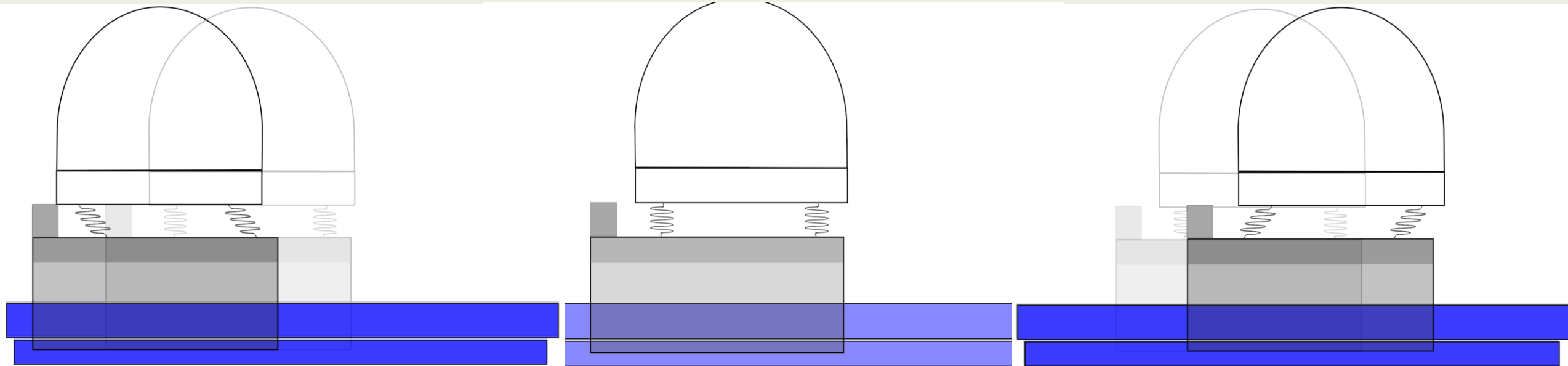




What happens here ?

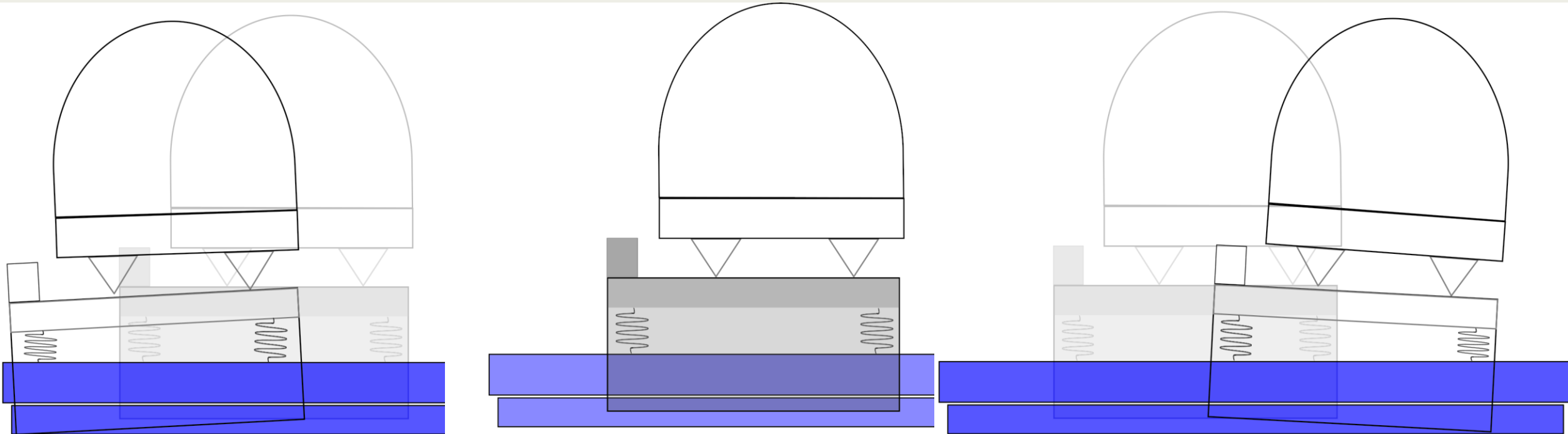


Sheering of seismometer feet (inertia driven)



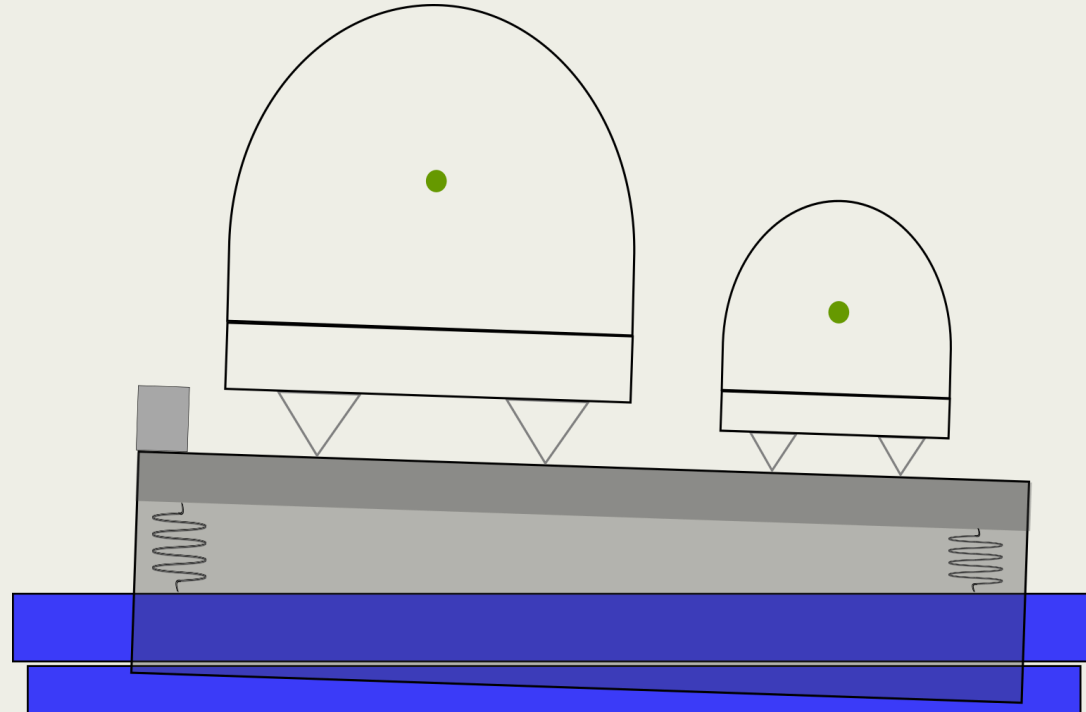
What happens here ?

Air bearing tilt (inertia driven)



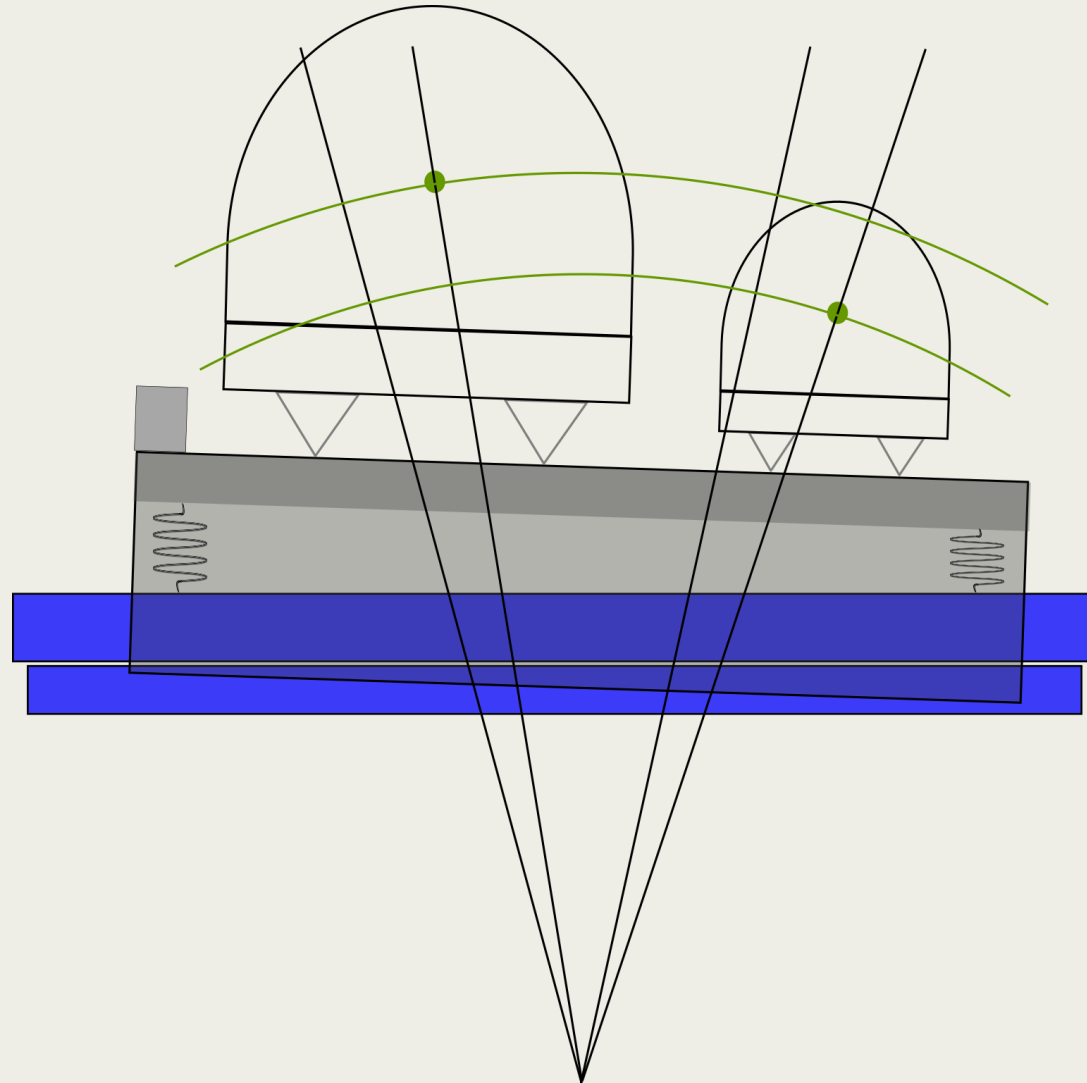
Dr. Thomas Bruns

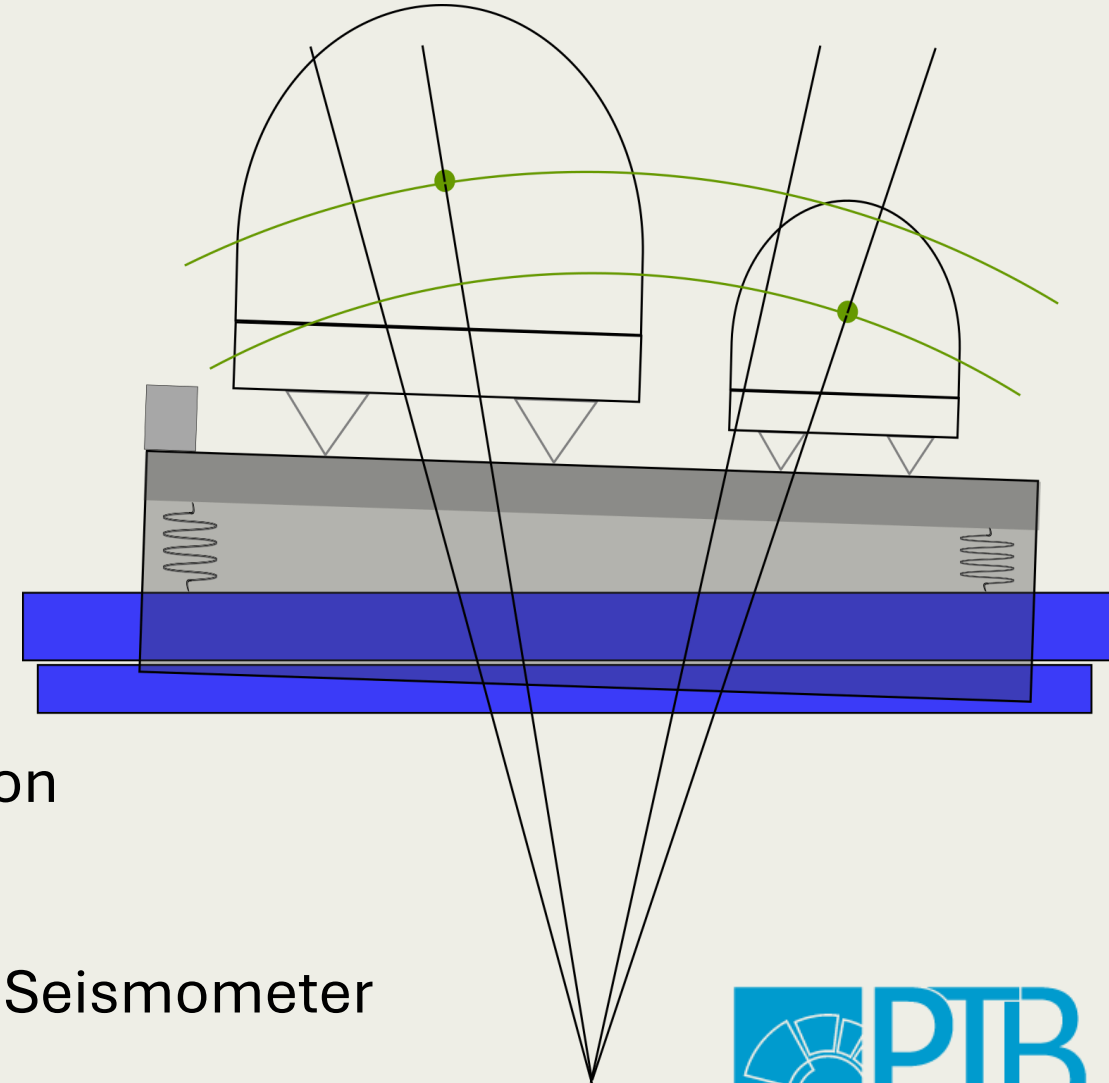
What happens here ?





What happens here ?

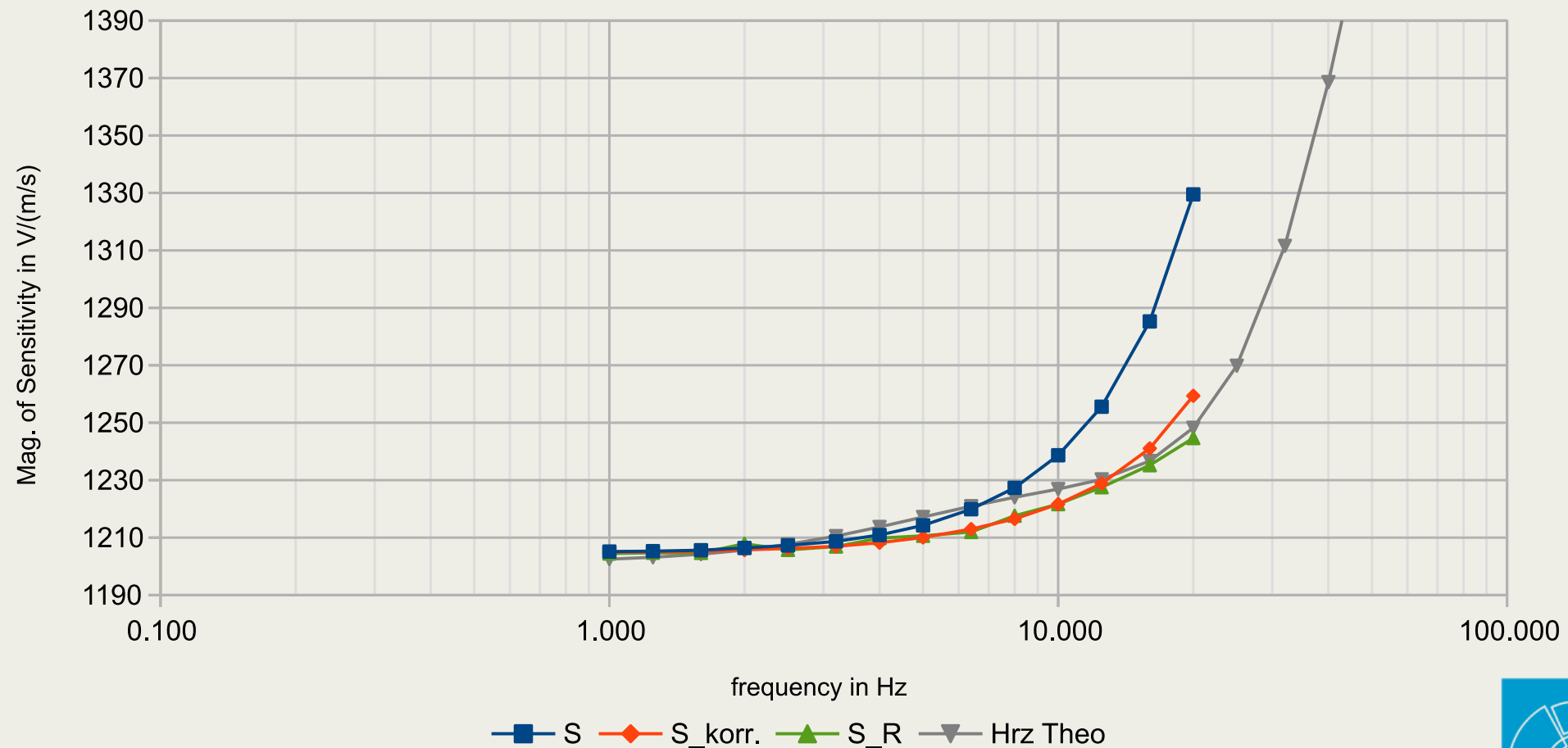






Does this help ...

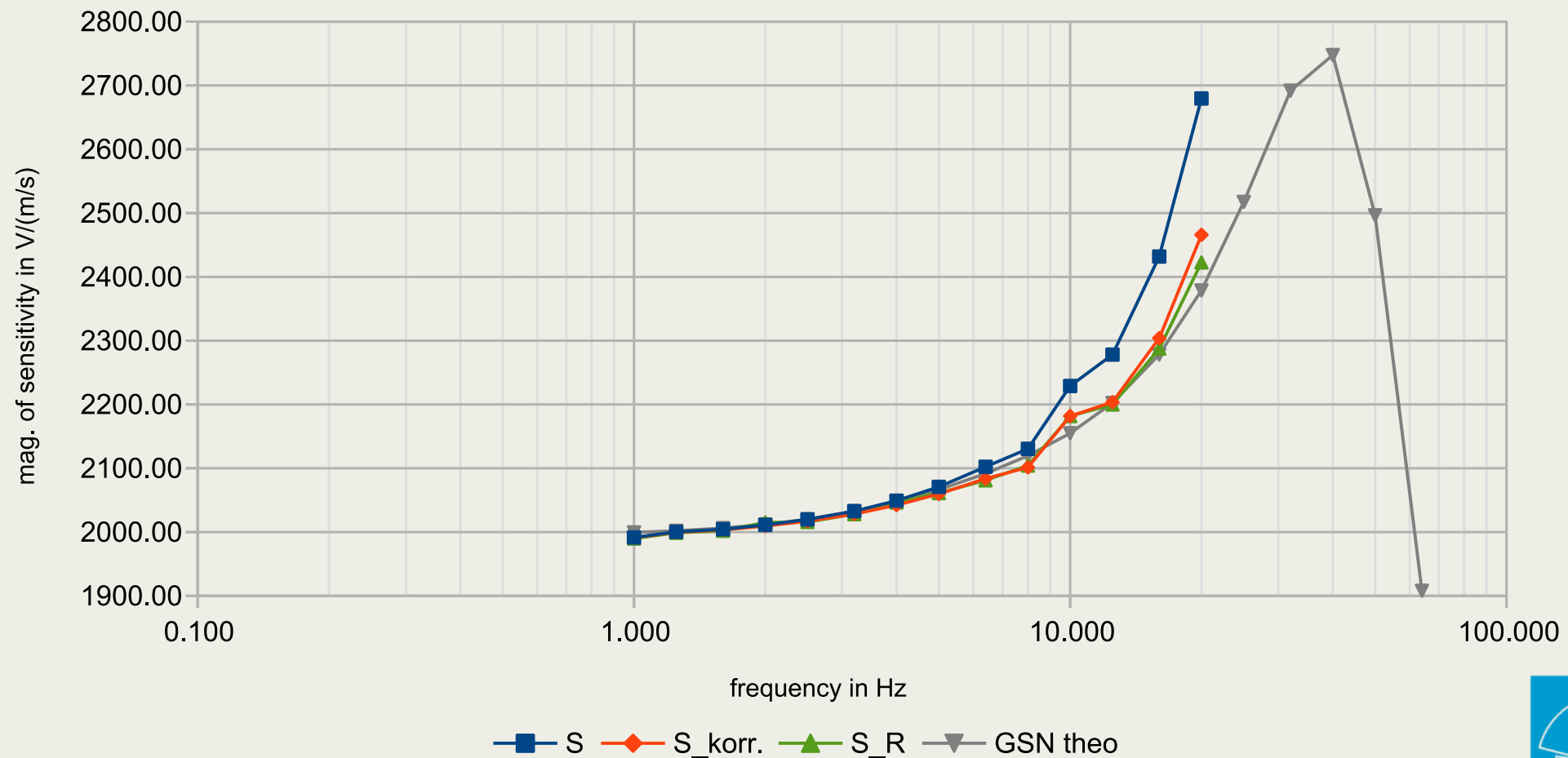
secondary calibration Horizon 120





Does this help ...

secondary calibration 360GSN





Summary

- **Primary calibration** with Laser-Doppler-interferometry works well from 0.1 Hz to 20 Hz (or more) if
 - the sensitive center location is known
 - dynamic tilt components are taken into account
- **Primary calibration** using tilt in the gravitational field works well from 1 mHz to 2 Hz if
 - the sensitive center location is known
 - or two measurements at different heights deliver the s.c.l., additionally
- **Secondary calibration** using a reference seismometer works from 10 mHz to 20 Hz if
 - the sensitive center location is known
 - dynamic tilt components are taken into account
 - a traceable calibrated reference seismometer is available (with suitable frequency range)