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Dynamic GNNs for Spatio-Temporal Seismic Event Localization and Characterization with Multimodal Integration

Christophe MILLET<sup>1,2</sup> Xavier CASSAGNOU<sup>2</sup>, Mathilde MOUGEOT<sup>2</sup>

> CEA, DAM, DIF, 91297 Arpajon, France ENS Paris-Saclay, 91190 Gif-sur-Yvette, France

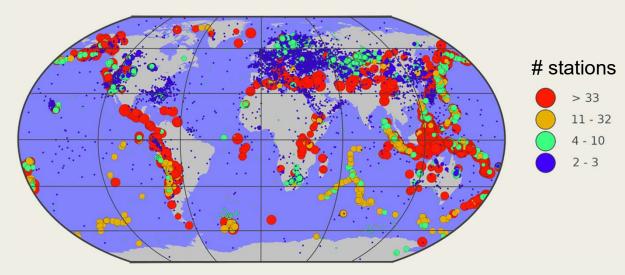
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# I Preliminaries



Map of seismic events (2014 - 2024) associated with at least one infrasound detection (REB), courtesy of H. Fauvel, CEA.





#### I - Preliminaries

• o o Characterization without graphs

## Using full-wave modelling[1]

- 10 seismic signals (▲): 1 1.5 kt TNT.
- 2 1 infrasound signal (▲): 0.1 0.25 kt TNT.
- 3  $10^2$  videos of blast waves:  $\sim 0.25$  kt TNT.

## **Based on empirical laws**

- Local magnitude (ML): 3.3 (USGS) or 3.8  $\pm$  0.1 (CEA)  $\Rightarrow$  0.1 0.6 kt TNT.
- Multi-technique analysis<sup>[2]</sup>: 0.13 − 2 kt TNT.

Based on Al? ⇒P2.1-716 (Noëlé, CM, Lehmann).

This work has been reviewed and approved by CEA for presentation at the conference SnT2025. No confidentiality restrictions apply to the material contained in this document.

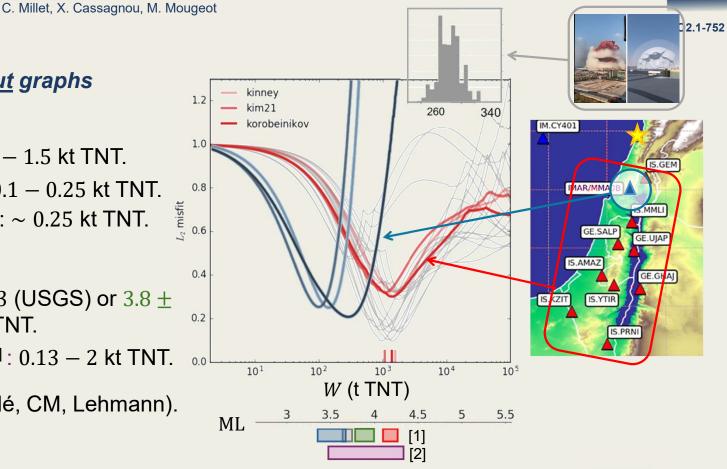


Fig.: Yield vs ML, Beirut (2020).



<sup>[1]</sup> Millet et al., ITW, 2023.

<sup>[2]</sup> Pilger et al., Scientific Reports, 2021.



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#### I - Preliminaries

o ● oo Graphs<sup>[3]</sup> are everywhere

**Graph = (vertices, edges) =** (V,E)

- Universal representation for structured data.
- Social networks (people, messages), biology
   (atoms/proteins, chemical bonds), sensor networks
   (stations, geodesic), recommendation (users/items, ratings),
   transportation (cities, roads/flights), ...

# Nodes and edges can carry information $X \in \mathbb{R}^{|V| \times C}$

- Node **features** ( $\mathbf{x}_j \in \mathbb{R}^{C}$ ): age/interests, charge/position, waveform/noise level, traffic load/delay at airport, ...
- Edge features  $(e_{ij})$ : distances, correlations, similarities, ...

 $X = (x_1, \dots, x_{|V|})$   $X = (x_1, \dots, x_{|V|})$ 

**Fig.**: Example of (V, E).

Learning tasks on graphs



Node-level, Edge-level, Graph-level

[3] https://ecoles-cea-edf-inria.fr/files/2025/06/GNN 2025 SummerSchoolCEAEDFINRIA Millet.pdf





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#### I - Preliminaries

### oo ● o An example of distributed data

#### What we know

- **Vertices** ( $\triangle$ ): French seismological network\*.
- **Features:** Station waveforms, positions of stations.
- **Data set**:  $n \sim 10^5$  seismic events (REB) recorded during 1995 – 2024.

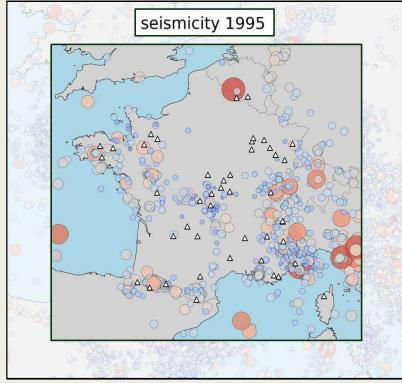
# What we don't know (and want to predict)

- **Edges**, relevant stations.
- Characteristics y of new earthquakes (magnitude ML, depth, location, ...), i.e. y = f(V, E, X).
- A way to adapt! Depending on the data available, relevant stations and edges can change.



ML

Fig.: EQ, FSN\*, 1995 – 2024



\*FSN: French Seismic Network.



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Convolution.

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#### I - Preliminaries

ooo f = Graph Neural Networks (GNNs)

### **Dynamic GNNs**

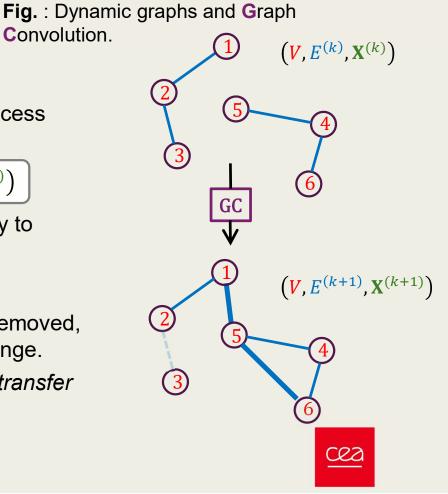
**Idea:** learn the **edges** implicitly during the training process using Graph Convolution (GC) layers:

$$(V, \emptyset, X) \rightarrow \cdots \rightarrow (V, E^{(k)}, X^{(k)}) \rightarrow \cdots \rightarrow (V, E^{(N)}, X^{(N)})$$

**Interpretability**: learning  $E^{(N)}$  offers a data-driven way to assess station relevance for each prediction  $(y_i)$ .

### Other advantages of GNNs

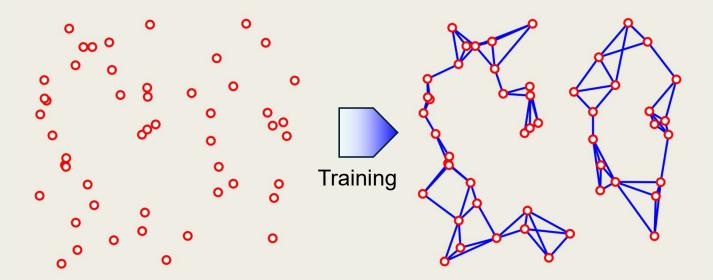
- Do not require a **fixed** input: **stations** can be added/removed, or repositioned over time; recording quality may change.
- Can handle graphs with **different** sets of **vertices** → *transfer* learning from one region to another.



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# II Graph Neural Networks







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### **II – Graph Neural Networks**

• ○ ○ How can we build edges? Theory

### The **Message Passing (MP)** paradigm:

$$\mathbf{x}_{j}^{(k)} \xrightarrow{\mathbf{AG} + \mathbf{UP}} \mathbf{x}_{j}^{(k+1)}.$$

- The AGregate step over the  $\kappa$ -hop neighbors controls the receptive field at each layer:  $AG = max(.), \Sigma(.), ...$
- The UPdate step refines the aggregated message by combining it with the node's current state.

# Who are the neighbors $i \in \mathcal{N}_j$ ?

- **Fixed**, through  $\kappa$ -nearest neighbors graph constructed from the geographic distances  $\mathbf{p}_i \mathbf{p}_j$ .
- Adapted, using similarities  $x_i$  between features.

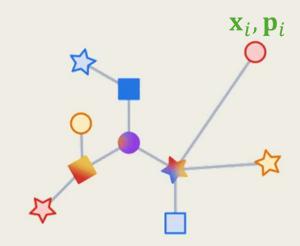


Fig. : Scheme of MP (Google Research Blog. 2024).





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### **II – Graph Neural Networks**

### ○ ◆ ○ The Spatio-Temporal GC block - Practice

**Edge generation:** each node j is connected to  $i \in \mathcal{N}_j$  which show maximum similarity

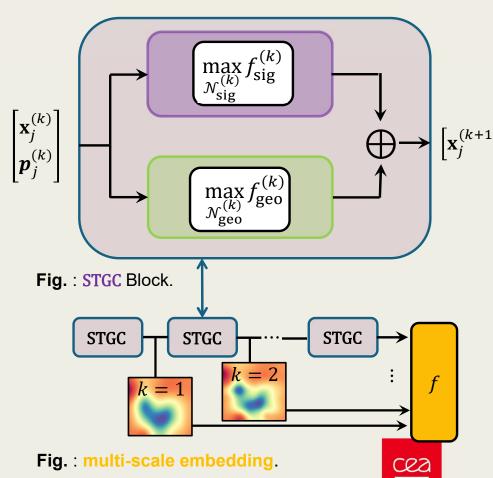
- Geographic proximity: nearby stations often observe similar signals  $\rightarrow \mathcal{N}_{geo}$ .
- Feature similarity: distant stations can exhibit similar waveform characteristics  $\rightarrow \mathcal{N}_{sig}$ .

Feature update: max pooling along the edges ji

$$\mathbf{x}_{j}^{(k)} \to \underbrace{f\left(\mathbf{x}_{j}^{(k)}\right)}_{\text{global}} + \underbrace{g\left(\mathbf{x}_{i}^{(k)} - \mathbf{x}_{j}^{(k)}\right)}_{\text{local}} \to \mathbf{x}_{j}^{(k+1)}.$$

 $\Rightarrow$ 4 neural networks  $(f,g) \times 2$  neighbors.

Multi-scale embedding: features produced by each STGC layer are concatenated.





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# II - Graph Neural Networks

oo ● Overview of the architecture

# **Dynamic-GNN**

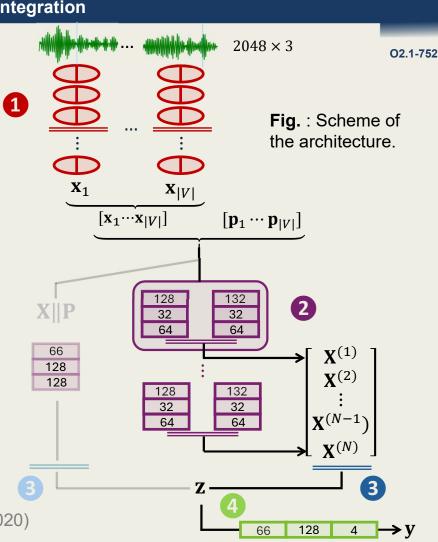


- 1 Convolutional Encoding: extraction of features using a CNN-based encoder  $\Rightarrow$  dim. reduction  $\Rightarrow$   $x_i$ .
- 2 Spatial feature fusion through N steps of STGC perceptive field is gradually enlarged.
- 3 Aggregation: condenses the information into a single fixed-size vector:  $\mathbf{z} = \max \mathbf{x}_j$ .
- 4 Prediction: extraction of graph-level seismic information  $\Rightarrow$  magnitude, depth, location (= y).

**Edgeless-GNN** 

(2)STGC are substituted to a MLP with  $X||P^{[4]}|$  as input.

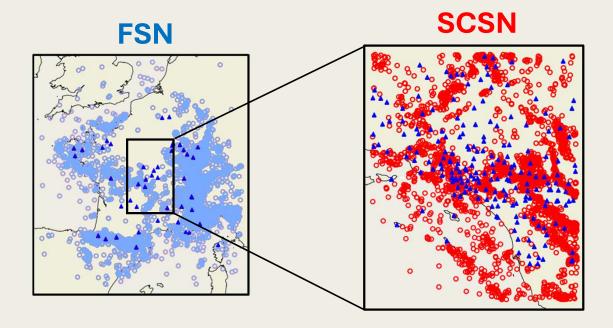
[4] van den Ende & Ampuero (2020)



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# III Numerical results





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ML > 2.5

#### III - Numerical results

• · · · · Datasets & processing

#### **Datasets:**

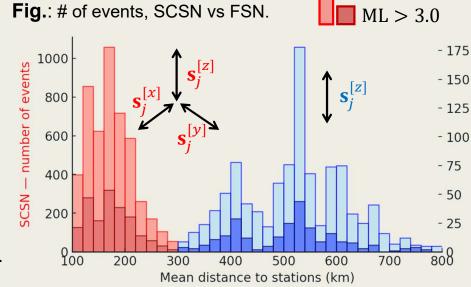
- **FSN**<sup>[5]</sup> (France): 2019–12/2021; |V| = 42.
- SCSN<sup>[6]</sup> (USA, CA): 2000–06/2019; |V| = 72.
- ML >  $2.5 \Rightarrow$  small datasets ( $\sim 1 \text{k events}$ ).

# Processing of signals $\mathbf{s}_{j}^{[.]} \in \mathbb{R}^{C \times P}$ (= features)

- # of components C = 1[z] or C = 3[x, y, z], time samples P = 2048, time windows 200 s or 100 s.
- Band-pass: 1 8 Hz or 1 1.5 Hz.

[5] https://renass.unistra.fr/

[6] https://www.fdsn.org



**Fig.**: 2021/01/02, ML  $\simeq 3.3$  (**FSN**)





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# III - Numerical results ○●○○○ Error metrics

# Separating data vs training variability

- k-fold cross validation: test sensitivity to dataset splits (90% - 10%) → data variability.
- Random seeds: repeat training with different initializations → optimization variability.

### Not a single training...

- 100 trainings per model (folds × seeds)  $\Rightarrow$  100 RMSEs;  $\sigma^2 = \frac{\sigma_{\text{opt}}^2}{\sigma_{\text{opt}}^2} + \frac{\sigma_{\text{dat}}^2}{\sigma_{\text{dat}}^2}$ .
- $\times$  **10's of GNN variants**<sup>[7]</sup>  $\Rightarrow$  10<sup>3</sup>'s of models, but today only the best one:



O2.1-752 Fig.: Ex. of k-fold for the French dataset (FSN). 2.5 3.5 4.5 90% 10% 2.5 3.5 4.5 2.5 3.5 4.5

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[7] see arxiv2025.



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#### **III - Numerical results**

**○○●○○ Impact of STGC\* on performance** 

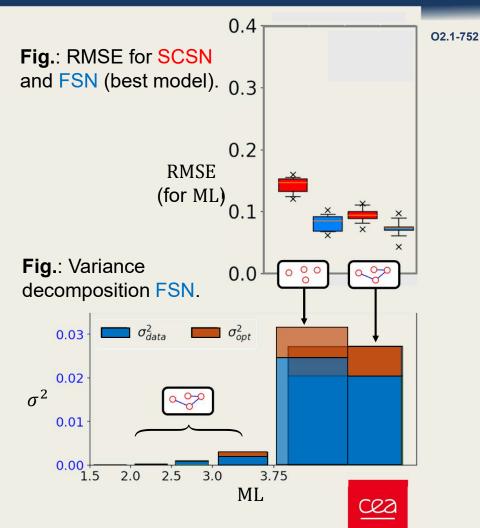
### Learned uncertainty

- Uncertainty learned:  $\pm 0.02$  vs  $\pm 0.3$  in most available bulletins (for ML  $\geq 2.5$ ).
- STGC reduces variance and bias compared to baseline (edgeless-GNN).
- Most variability comes from large magnitudes variability ( $\sigma \simeq 0.14$  for ML > 3.75  $\leftrightarrow$  42 events!), but stays below operational benchmarks ( $\pm 0.3$ ).

\*Spatio-Temporal Graph Convolution

SCSN: Southern California Seismic Network

FSN: French Seismic Network.





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#### III - Numerical results

### **○○○●○** Impact of STGC on Robustness

### Signal degradation steps

- Waveforms are degraded to mimic more realistic, noisy conditions: 1 ⊃ 2 ⊃ 3.
- 1) Full spectrum (1-8 Hz).
- ② Narrow band (1-1.5 Hz).
- 3 Random time shift (-100 to 100 s).



#### Results

- STGC enhances robustness.
- Multi-scale embedding stabilizes learning for deeper architectures.

**Fig.**: RMSE for magnitude, showing robustness as inputs are degraded.

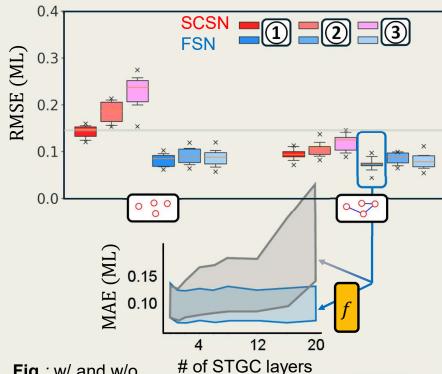
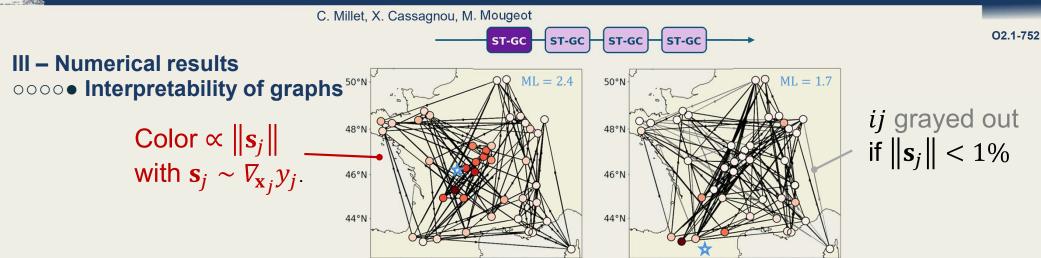


Fig.: w/ and w/o embedding.

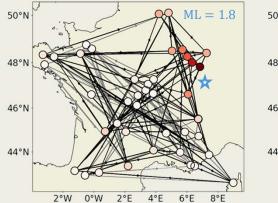
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#### Not a black-box:

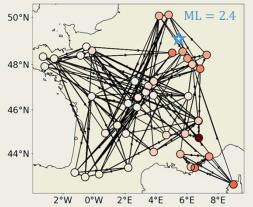
- STGC (2) learns spatial attention mechanism.
- Max pooling (3) condenses and reveals key stations.



2°E

4°E

6°E



2°E

4°E

6°E

0°W

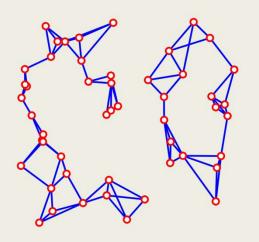
**Fig.**: Scores (ML) across STGC layers for new events.



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# **Multimodal integration**





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COURM	0.04		Sg	2024/	10/22	09:49	:10.3	-0.1		
MRGE	0.09	142.6 m	Pg	2024/	10/22	09:49	:10.7	0.2		
MRGE	0.09	142.6 m	Sg	2024/	10/22	09:49	:12.4	0.5		
REMY	0.13	98.9 m	Pg	2024/	10/22	09:49	:11.1	-0.1		
REMY	0.13	98.9 m	Sg	2024/	10/22	09:49	:13.2	0.1		
HOUCH	0.15	286.3 m	Pg	2024/	10/22	09:49	:11.6	0.1		
HOUCH	0.15	286.3 m	Sg	2024/	10/22	09:49	:13.8	0.2		
SEMOS	0.21	352.1 m	Pg	2024/	10/22	09:49	:12.7	-0.0		
SEMOS	0.21	352.1 m	Sg	2024/	10/22	09:49	:15.6	-0.0		
SALAN	0.29	359.4 m	Pg	2024/	10/22	09:49	:14.1	0.0		
SALAN	0.29	359.4 m	Sg	2024/	10/22	09:49	:17.8	-0.1		





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### IV - Multimodal integration

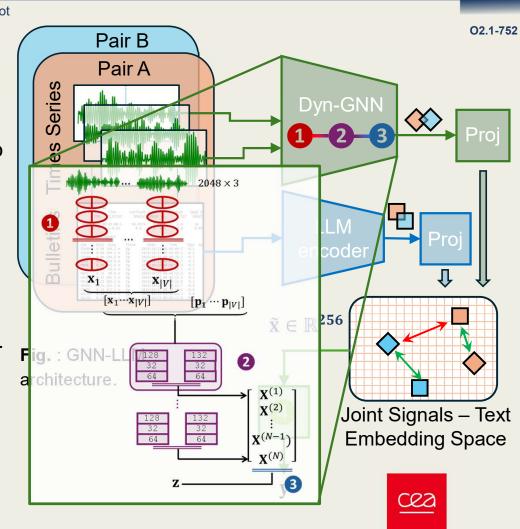
• o Principle

**Architecture:** 2 pretrained modality-specific models:

- Dynamic-GNN processes data from stations to produce embedding + Proj head.
- Text encoder fined-tuned\* to the technical language of bulletins ("expurged" of the predicted values) + Proj head.

**Hybrid loss:**  $l_{\rm I} + \lambda l_{\rm II} + \mu l_{\rm III}$ 

- I. Alignment: InfoNCE (contrastive objective).
- **II.** Regularization: KL, Gutenberg–Richter.
- III. Supervised head (lightweight)  $\tilde{x} \mapsto y$  to ensure calibration while reducing bias.
- \* LLaMA-3 (Meta) + LoRA/QLoRA, persp.: "SeismoBERT".





# Events

1011

3435

7030

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**Tab.**: Pred. ML – ML (FSN).

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# IV – Multimodal integration

○ First results

### **Training & validation:**

- Training on FSN catalogue (waveforms + derived bulletins\*, 2019–2021) for ML>1.5.
- Validation against external agencies (ETHZ MLv, EMSC/EPOS) via ML(Pred)-MLv(ETHZ).

#### First trends

- GNN-only: systematic bias +0.3 vs MLv (ETHZ), and -0.2 vs ML (RMSE~0.14).
- GNN+LLM reduces the bias (+0.1 vs 0.3) but so far only on the common dataset FSN ∩ ETHZ.

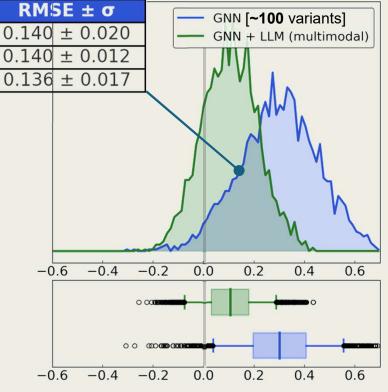


Fig.: Predicted ML – MLv (ETHZ).



<sup>\*</sup> Without predicted ML, depth, loc.



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# **Key outcomes & perspectives**

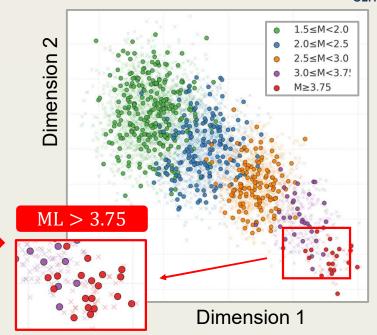
### **Dynamic-GNNs:**

- Accuracy/robustness: ~1k events already yield nearexpert performance, even with low spectral richness!
- **Interpretability:** Dynamic graphs reveal the key stations, that can be compared to that analysts rely on.
- + LLM: corrects bias, links waveforms 
   ⇔ bulletins, classifies unseen events (zero-shot classification).

#### **Limitation:**

- Preliminary results on research datasets: to be consolidated on larger & diverse catalogs.
- Need for global associator to select waveforms yet GNNs can self-associate (PLAN<sup>[8]</sup>).

[8] Phase picking, Location, and Association Net. (Xu Si et al., Nature, 2024).



**Fig.**: Waveforms (x) and bulletins (●), visualized using PCA and t-SNE.



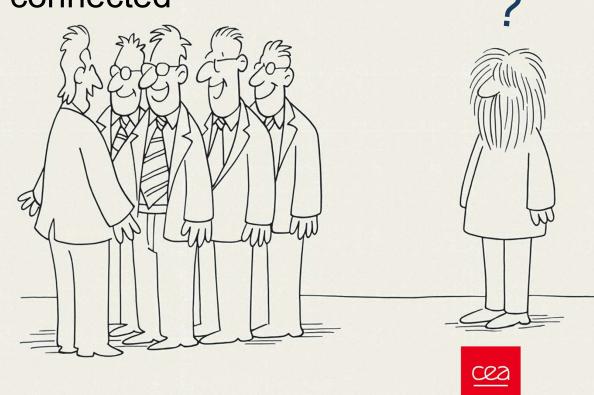
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# Thanks for attention! And may your graphs stay connected

**Special thanks** to the invisible crowd of AI assistants (GPT-5, ...) — still working on inclusivity too!

Paper: arxiv2025.



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# What's next?

#### **Robustness & trust:**

- Self-adaptive dyn-GNN for the IMS ("I'm thinking" analogy).
- Scalable methods and confidence metrics for automatic detections and event characterization.
- Privacy, distillation & unlearning for sensitive data.

### **Graph Foundation Models:**

- GFMs for multimodal IMS data (stations, signals, events).
- Breaking silos across seismic, infrasound, hydroacoustic & radionuclide networks.
- Integration of LLMs as graph nodes/agents → acting like analysts and interacting with databases, physical models...

